

Simulation of MEMS Based Flexible Flow Sensor for Biomedical Application

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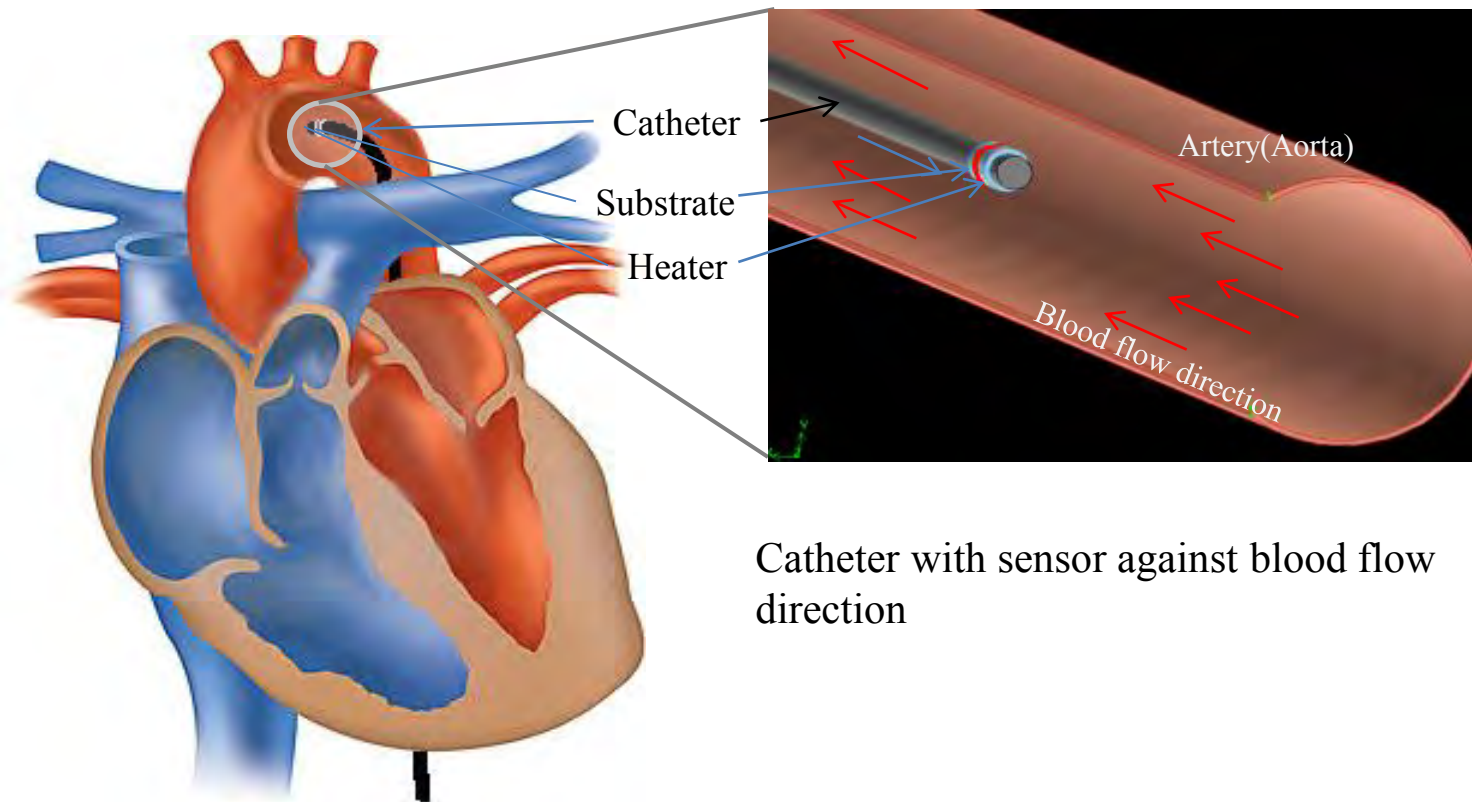
Presentation Overview

- **Aim**
- **Hot-wire Anemometry Principle**
- **Literature Survey**
- **Sensor Development**
 - Heater Selection & Design
 - Substrate Selection
 - Sensor Geometry
- **Steady State Analysis**
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 - Velocity distribution
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 - Velocity profile
 - Pressure profile
- **Conclusion and Future scope**
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Aim

Development of MEMS Based Flexible Flow Sensor for Health Care Monitoring



Catheter with sensor against blood flow direction

Catheter Pathway through Aorta

SENSOR SETUP

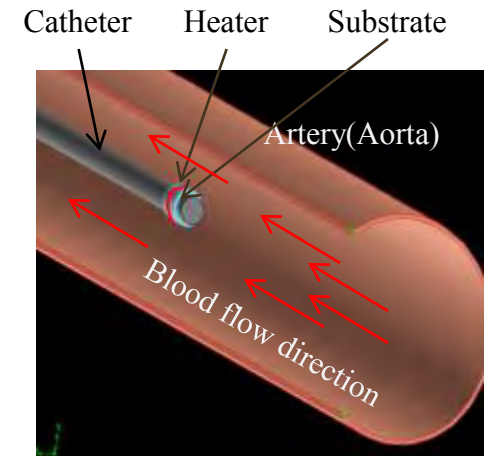
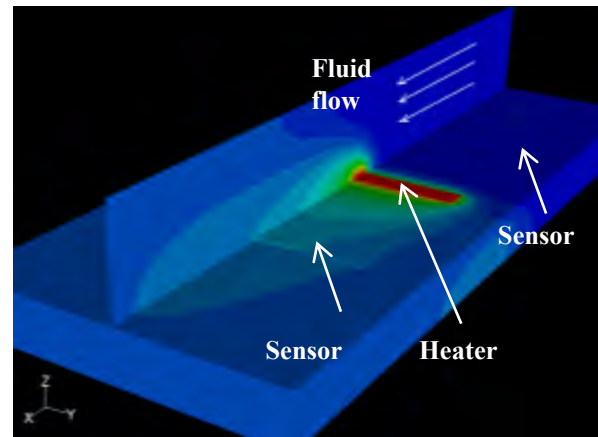
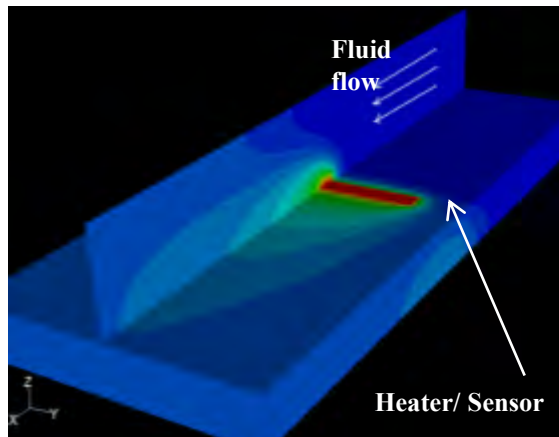
Hot-wire Anemometry Principle

Principle (*Hot-wire Anemometer*):

Fluid velocity is determined by the amount of heat dissipated in the fluid from the electrically heated sensing element exposed in the fluid medium.

Types:

- 1) Single Hot Wire Anemometer
- 2) Multi Hot wire Anemometer



Heat transfer mechanisms: Conduction and Convection.

At equilibrium: Input power ($I^2 R_w$) = power lost $h.A_w(T_w - T_f)$ to convective heat transfer

$$I^2 R_w = h.A_w(T_w - T_f)$$

I : input current

R_w : Resistance of the wire

h : Heat transfer coefficient of the wire

A_w : Projected wire surface area

T_w & T_f : temperatures of the wire and fluid respectively

Wire resistance R_w at temperature T_w is given by:

$$R_w = R_{Ref} [1 + \alpha(T_w - T_{Ref})]$$

T_{Ref} : Reference temperature

R_{Ref} : Reference resistance of wire

α : Temperature coefficient of resistance of wire's material at T_{ref}

According to King's law, The heat transfer coefficient h is a function of fluid velocity v_f

$$h = a + b.v_f^c$$

a , b , and c are coefficients obtained from calibration-

a : combination of effective area of thermal element, stream wise length, heat capacity, thermal conductivity and viscosity of the fluid.

b : conductance heat loss to the surface.

c : 1/3

v_f : Fluid velocity

Hence, fluid velocity is given by:

$$v_f = \left\{ \left[\frac{I^2 R_{Ref} [1 + \alpha(T_w - T_{Ref})]}{A_w(T_w - T_f)} - a \right] / b \right\}^{1/c}$$



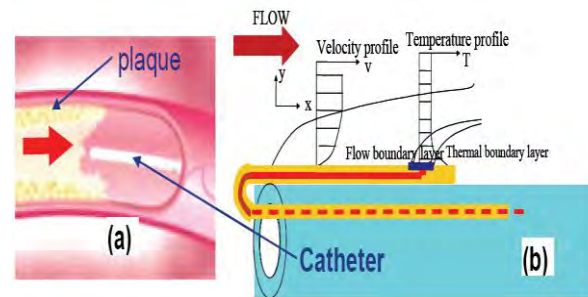
$$I^2 \propto v_f^{1/3}$$

Literature Survey

- **Shear Stress Sensor** –

1) Disturbed blood flow at arterial bifurcations is considered to be an inducer of vascular oxidative shear stress that promotes the initiation and progression of **atherosclerosis**.

2) A micromachined flow shear-stress sensor based on thermal transfer principles have been developed by *Tzung k. Hsiai et al.*



- **Pressure sensor** –

1) Disposable CMOS Catheter-tip Pressure Sensor For Intracranial Pressure Measurement by *Li-Anne Liew et al, University of Colorado, USA*.

2) Silicon flow sensor with on-chip CMOS readout electronics over catheter surface have been reported by *R. Kersjes et al*.

3) A combination of blood pressure/flow/oxygen sensor chip has been developed at the *Delft University of Technology* that can be fitted to a catheter.

- **Our Method** –

Development of flow sensor for detection of stenosis by measuring the change in blood flow through anemometric principle.

Sensor Development

➤ *SIMULATION ANALYSIS (using COMSOL 4.1):*

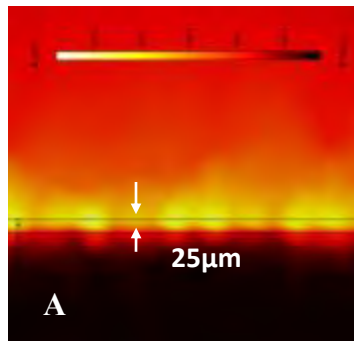
- Heater Material Selection,
- Heater design,
- Substrate Selection,
- CFD Analysis : Velocity and Temperature distribution near the sensor and catheter tip with catheter insertion into the blood stream.
 - ✓ Steady state analysis
 - ✓ Transient analysis



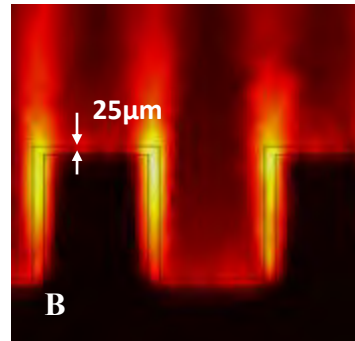
Heater Selection & Design

HEATER SELECTION:

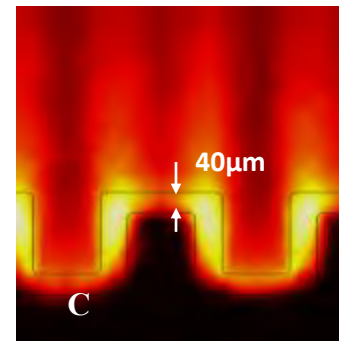
- Nichrome was chosen as the heater material due to very high TCR value.
- High stability over a wide range of operating temperature.



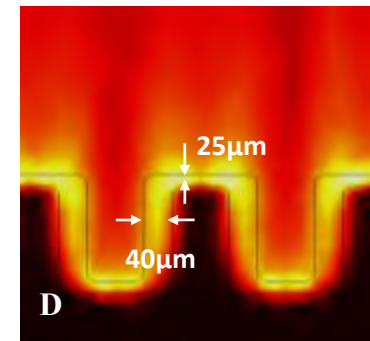
Straight Heater (width= 25 μ m)



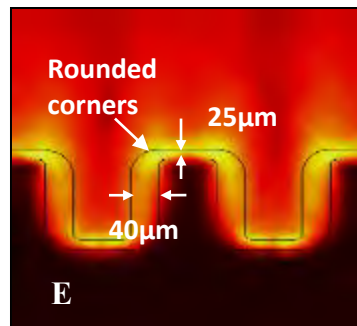
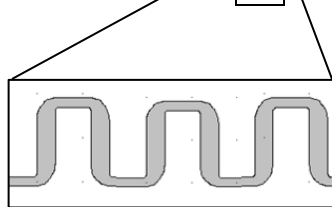
Meanderline Heater structure (width= 25 μ m)



Meanderline Heater structure (width= 40 μ m)



Meanderline Heater structure with varying width (width= 25 & 40 μ m)

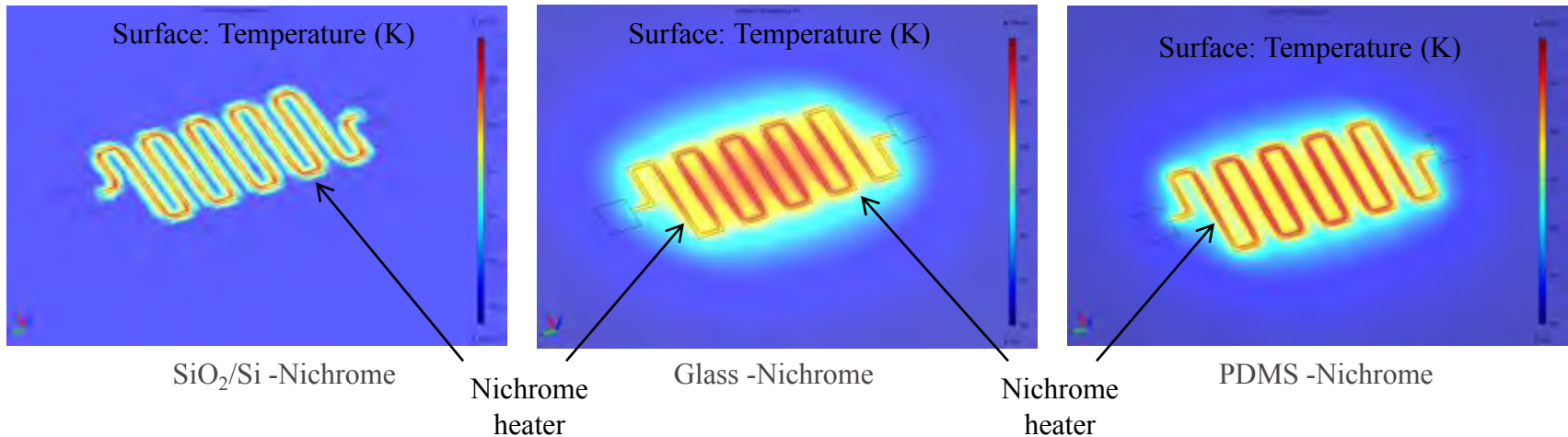


Meanderline Heater structure with rounded corners (width= 25 & 40 μ m)

HEATER DESIGN:

- Uniform Heat distribution (Fig. E).
- Heater length : ~ 9 mm to mount around a catheter of diameter 3 mm.
- Resistance value: ~ 2 k Ω

Substrate Selection



*Substrate Area: 1cm x 1cm x 1mm; $\Delta T \sim 6K$; Ambient temperature = 300 K; $R = 2.2 \text{ k}\Omega$

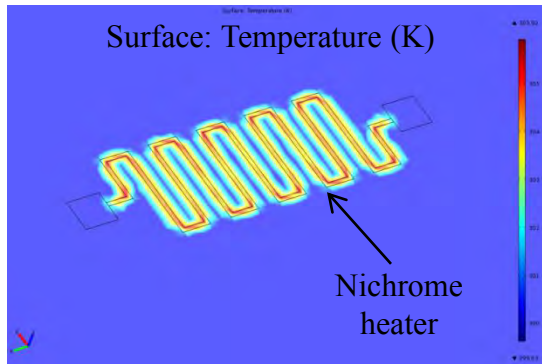
SiO ₂ /Si -Nichrome	Glass-Nichrome	PDMS-Nichrome
Max. Heater Temp- 305.9K	Max. Heater Temp- 306.1K	Max. Heater Temp- 305.85K
Voltage i/p- 22 V	Voltage i/p- 9 V	Voltage i/p- 4.2 V
Power – 217.8 mW	Power – 36.9 mW	Power – 7.98 mW

SUBSTRATE SELECTION:

PDMS was selected over SiO₂ or glass as substrate for Nichrome heater due to:

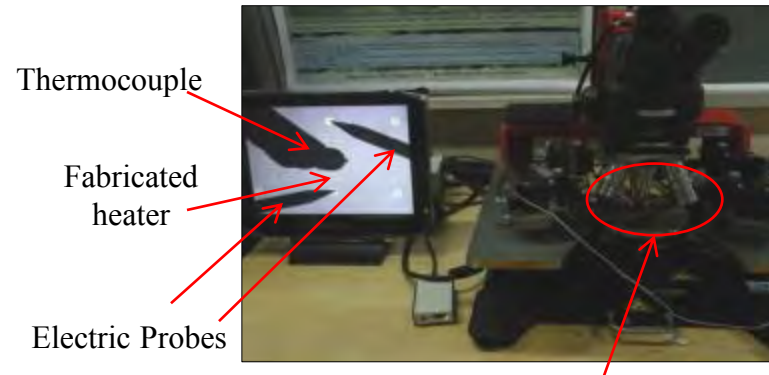
- Less power requirement to attain similar temperature increment due to low thermal conductivity of PDMS.
- Biocompatibility, flexibility and ease of fabrication.

Simulated Heater



SiO₂/Si -Nichrome

Fabricated Heater



Nichrome heaters over SiO₂/Si substrate

	Simulated Results	Tested Results
Voltage i/p (V)	22 V	25 V
Temperature increment (ΔT)	$\Delta T = 6.3$ K	$\Delta T = 6$ K
Resistance Change (ΔR)	$\Delta R = 8.3$ Ω	$\Delta R = 7$ Ω

Simulation
Details:

Substrate Area: 1 cm x 1 cm x 1 mm;

Ambient temperature : 300 K;

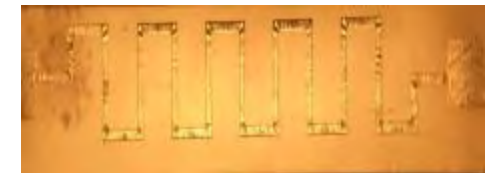
Thickness : 0.2 μ m;

Physics: Electric Currents, Shell (ecs)
 Heat Transfer 2 (ht2)

Linearized resistivity;

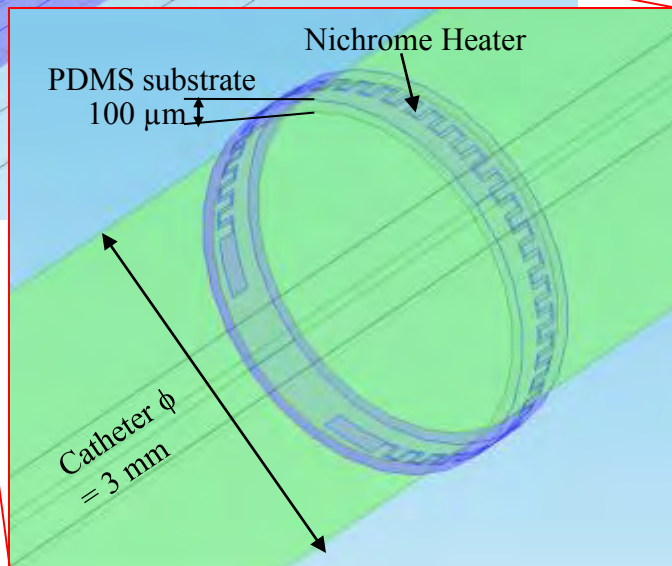
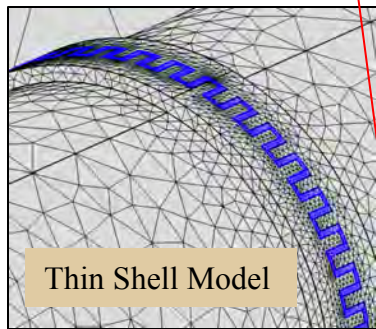
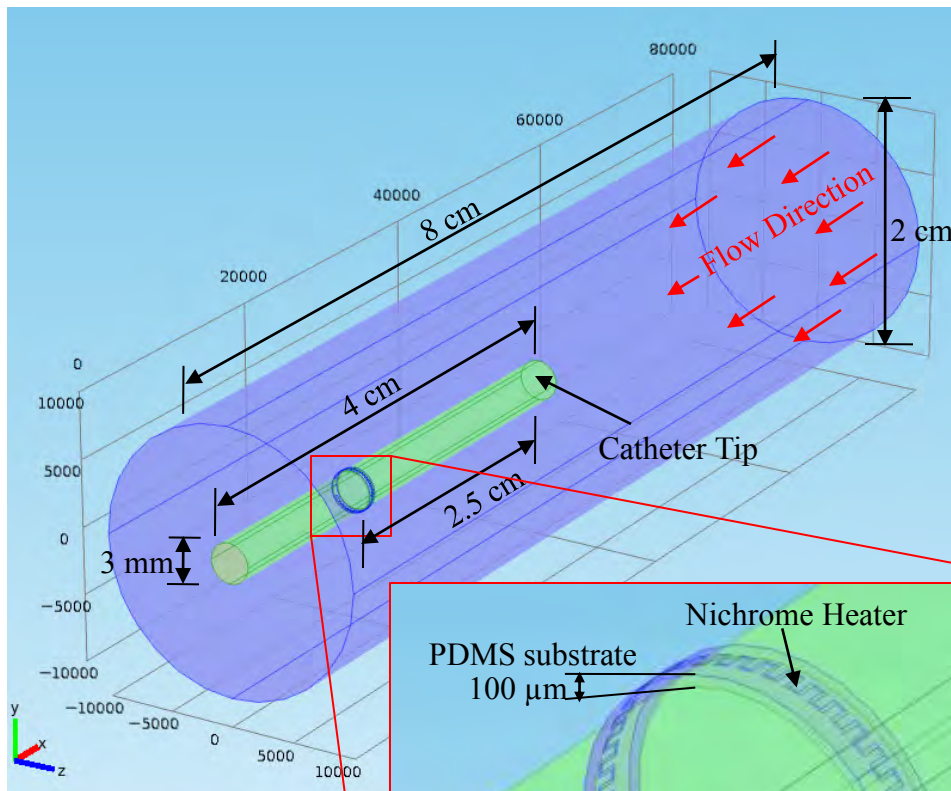
Two way coupling: Heat source \rightarrow ecs.Qrsh

Temperature for current conservation \rightarrow ht/solid1



Fabricated Nichrome micro heaters over PDMS substrate

Sensor Modeling



Blood Vessel length = 8 cm

Blood Vessel diameter = 2 cm

Catheter length = 4 cm

Catheter diameter = 3 mm

Sensor Position = 2.5 cm from catheter tip

PDMS substrate thickness = 100 μm

Nichrome Heater thickness = 0.2 μm

Blood velocity = 0.2 m/s (-x axis)

Physics =

- Electric Currents, Shell (*ecs*)
- Electric Potential
- Conjugate Heat Transfer (*htcf*)
- Temperature
- Velocity

Linearized resistivity

Two way coupling = Heat source \rightarrow *ecs.Qrsh*
 Temperature for current conservation \rightarrow *ht/solid1*

Mesh = Free tetrahedral

Ambient temperature (body) = 310 K (37 °C)

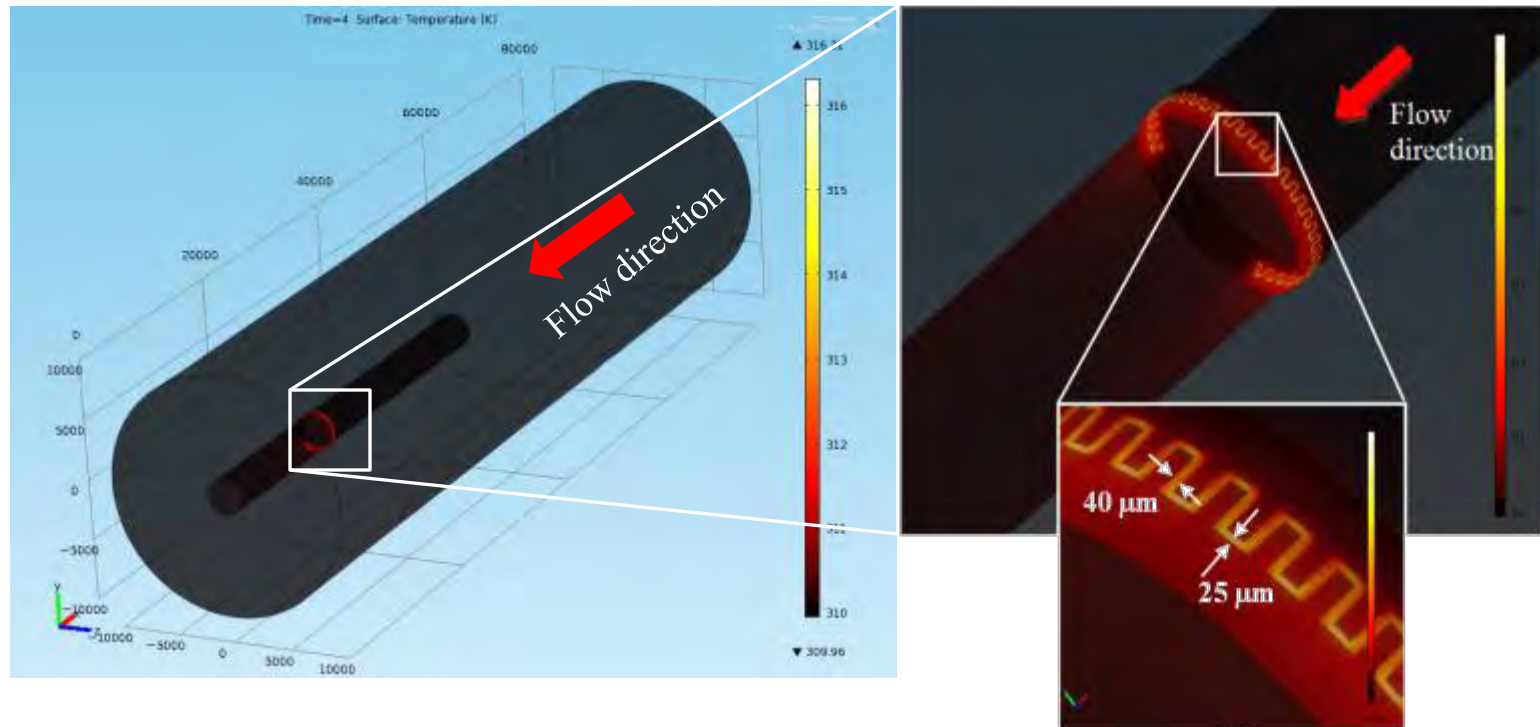
Temperature increment = 5K

Steady State Analysis

COMSOL Equation: Heat Transfer in Fluids solves the following equation for temperature, T

$$C_p \frac{\partial T}{\partial t} - \Delta \cdot (k \Delta T) + \rho C_p U \cdot \Delta T = Q$$

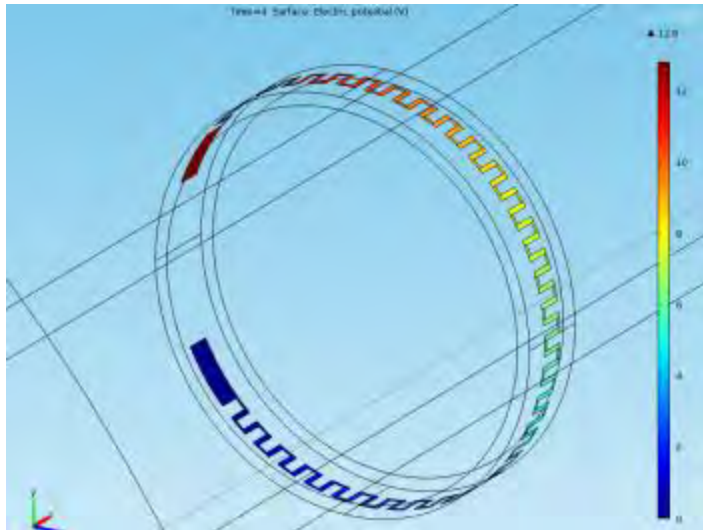
ρ is the density,
 C_p is the heat capacity,
 k is the thermal conductivity,
 U is the fluid velocity and
 Q is the heat source (or sink)



Temperature distribution = 315 K over the heater surface.

Meanderline heater structure with varying edges (25 μm & 40 μm) having a uniform temperature distribution.

Steady State Analysis



Electrical Potential distribution

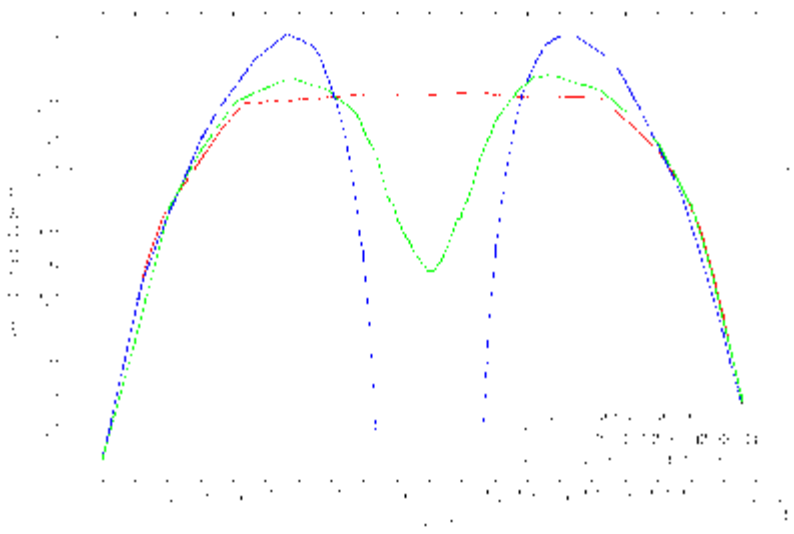
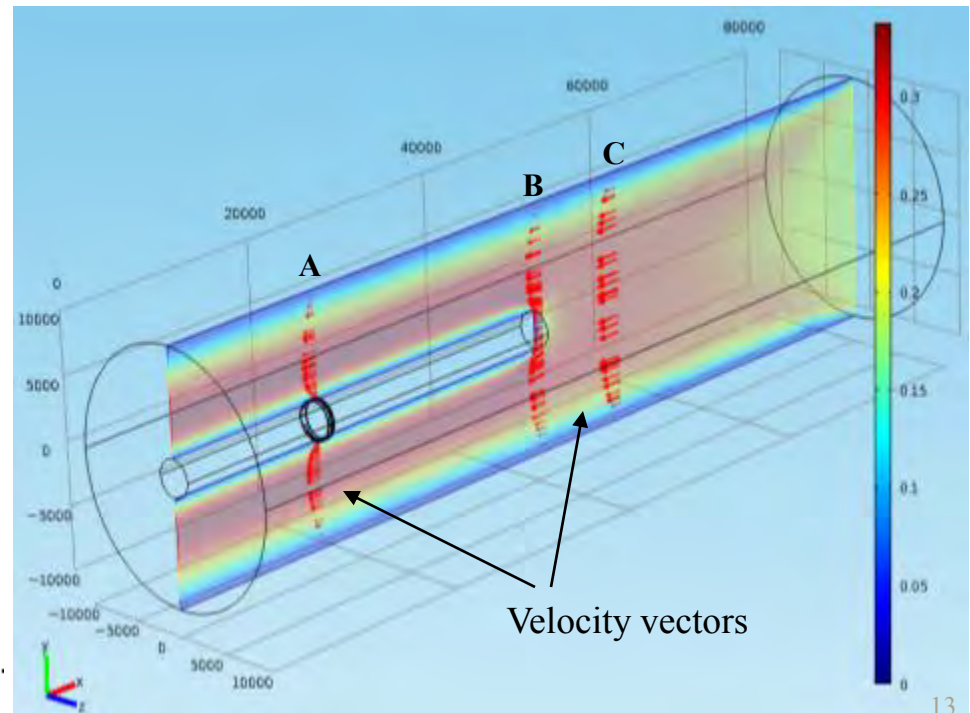
I/p voltage req. = 12.8 V

Power req. = 60 mW

$\Delta T = 5K$

Velocity distribution

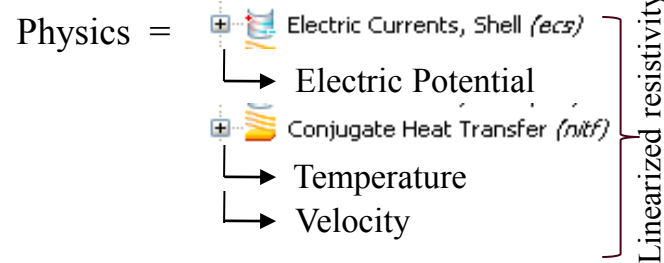
= across blood vessel cross section with catheter



Transient Analysis

Simulation
Details:

Blood velocity = 0.2 m/s (-x axis)



Two way coupling = Heat source \rightarrow ecs.Qrsh

Temperature for current conservation \rightarrow ht/solid1

Mesh = Free tetrahedral

Ambient temperature = 310 K (37 °C) [Body temperature]

Temperature increment = 5K

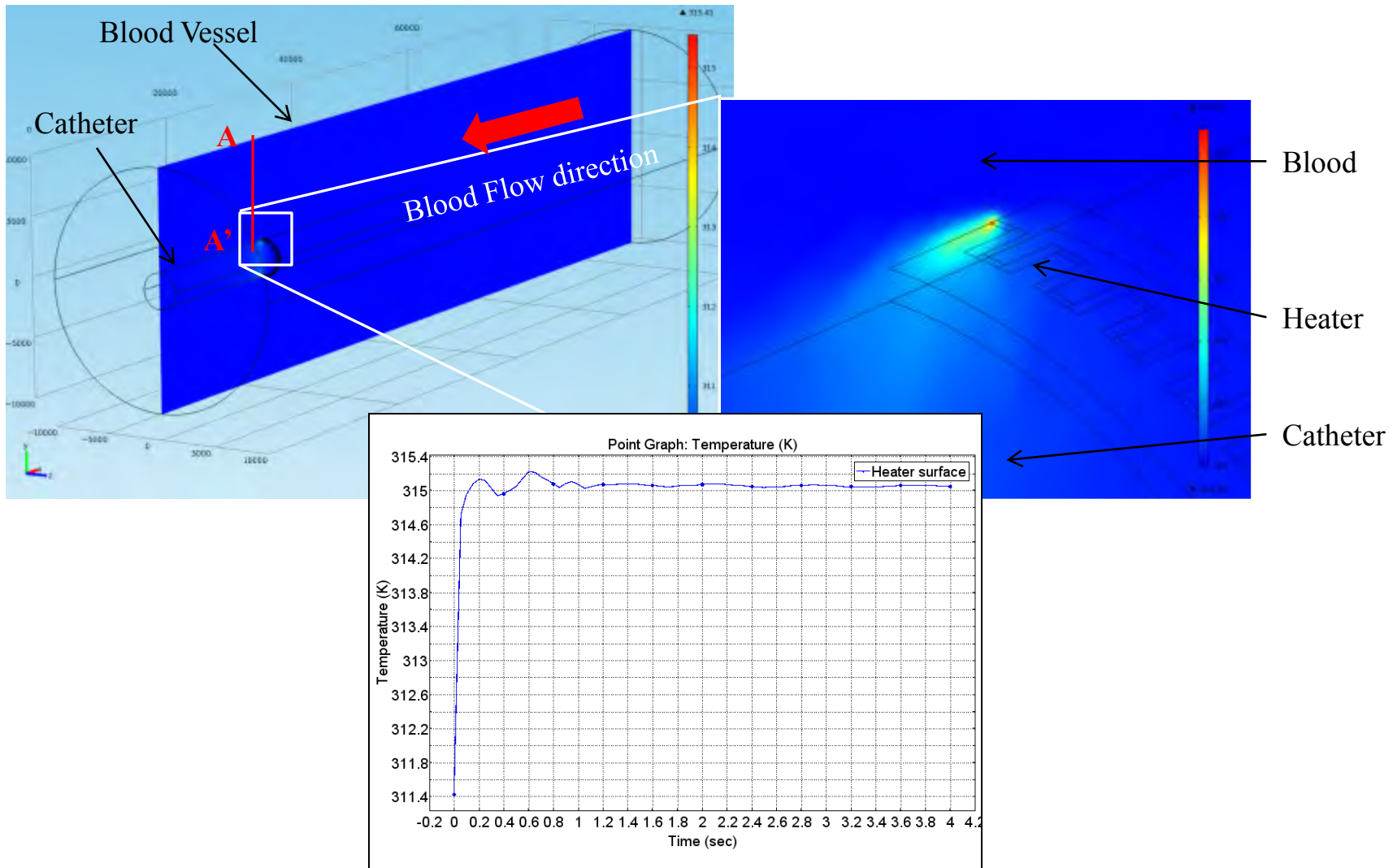
Study (Time dependent) :

Range = (0, 0.05, 4)

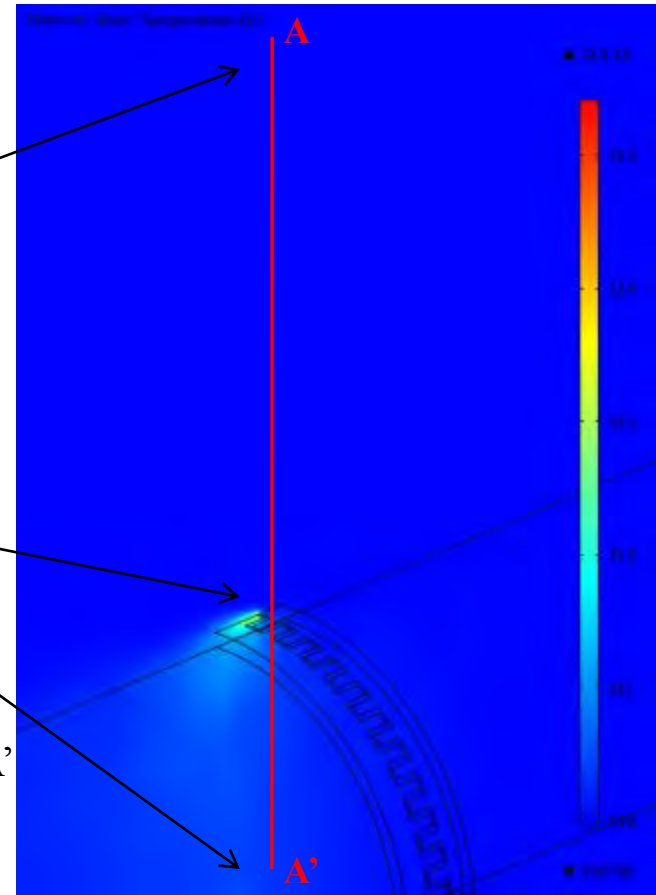
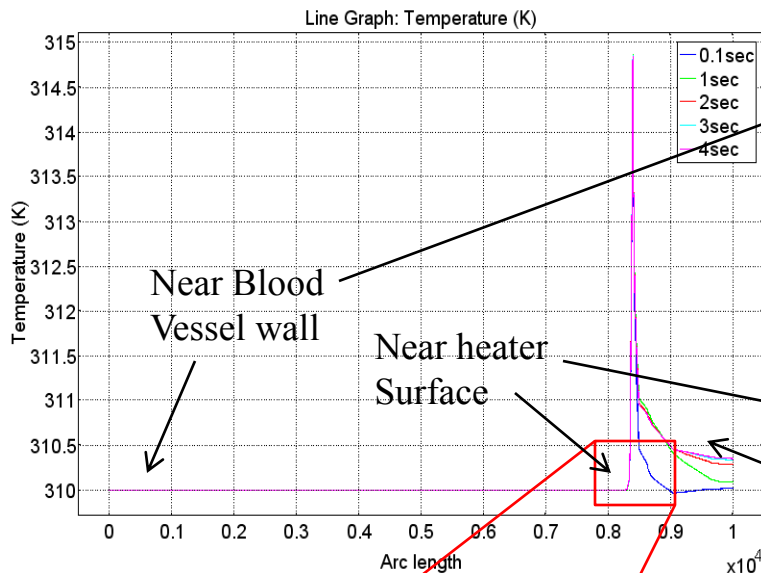
Time stepping method = Generalized alpha

Remaining conditions = default settings

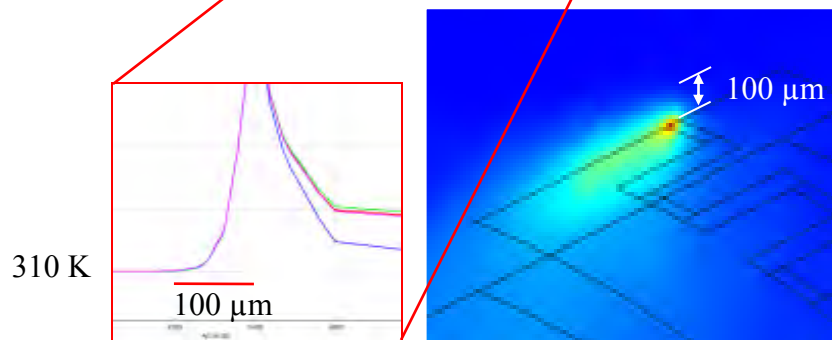
Temperature profile



Transient analysis of temperature profile showing a rise time of 0.2 sec to increase the heater temperature by 5 K

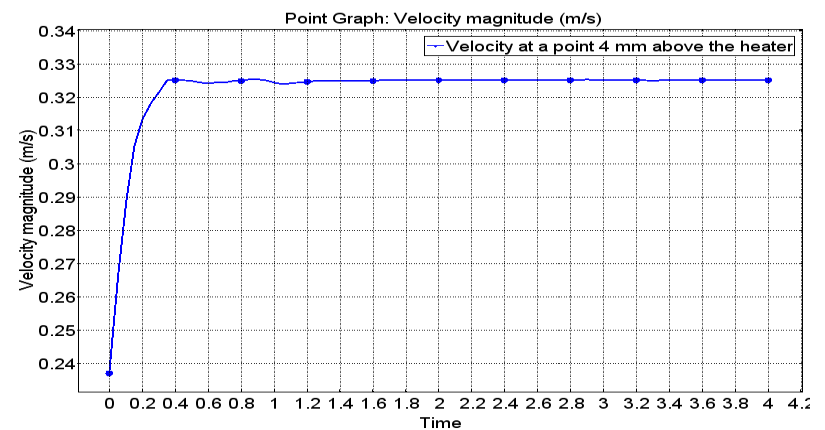
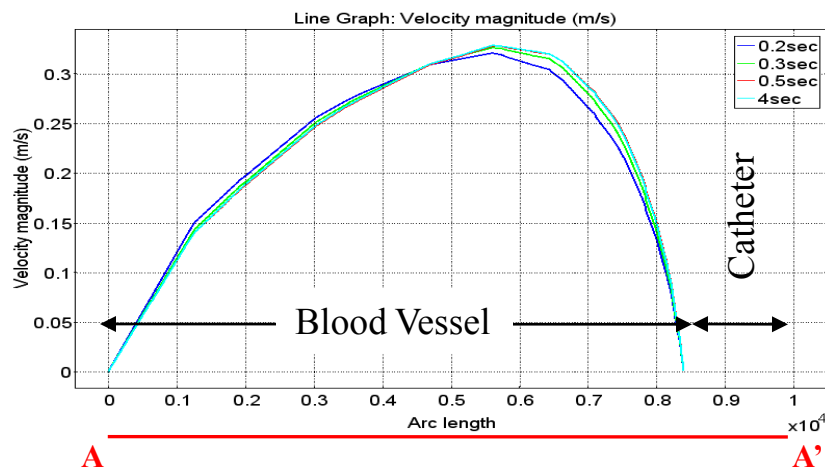
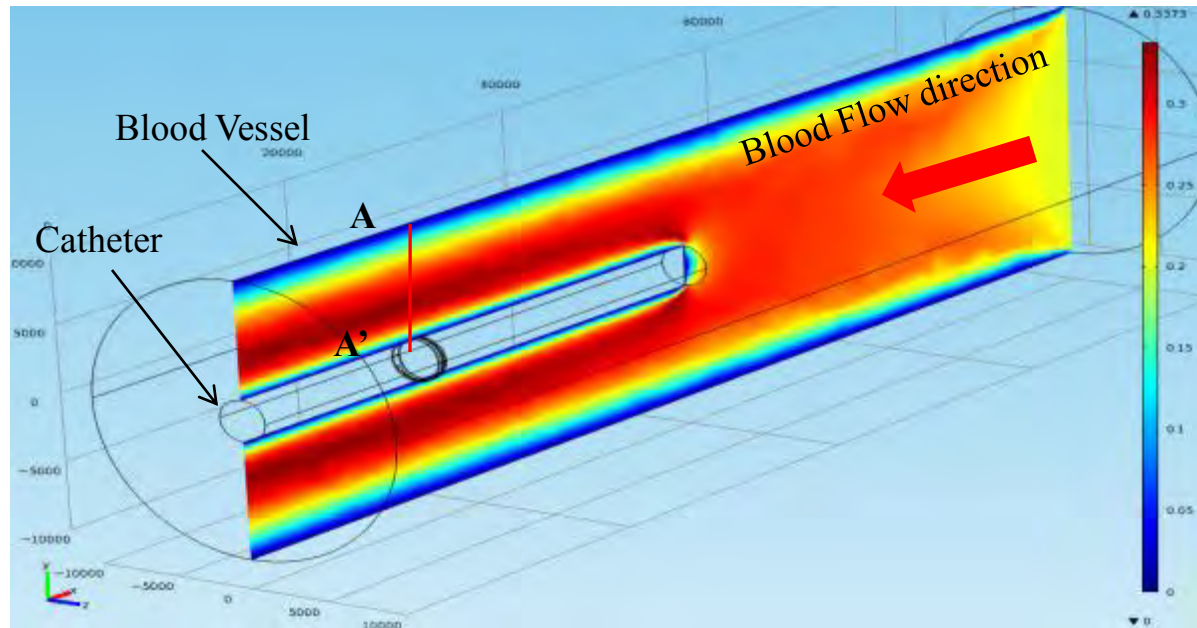


Variation of temperature profile across the blood vessel A-A'



Temperature settles to normal body temperature of 310 K within about 100 μm above the heater surface.

Velocity profile



Velocity settling time = 0.4 sec

Conclusion and Future scope

Conclusion

- **Meanderline heater structure** with varying edges (25 μm & 40 μm) was chosen as the final heater design having a *uniform temperature distribution*.
- **Nichrome** was chosen as the *sensing element* due to its high TCR and high stability
- **PDMS** was chosen as the *substrate material* due to its low thermal conductivity and flexible and biocompatible nature.
- **Simulated** test heater results were verified with a similar **fabricated** heater
- **Steady state analysis** was performed for the sensor wrapped around the catheter
 - > 12.8 V for $\Delta T = 5\text{K}$ (315K)
- **Transient analysis** was performed:
 - *Temperature rise time* = 0.2 sec
 - *Velocity settling time* = 0.4 sec

Future scope

- Simulation of the sensor at varying positions over the catheter surface.
- Simulation of the sensor/catheter assembly near the wall of the blood vessel.
- Simulation of velocity/temp profile with pulsatile blood velocity in presence of catheter.
- Simulation of velocity/temp profile near a stenosis with/without the catheter.
- Simulation of multi hot wire anemometer assembly with multiple sensors over the catheter.



References & Acknowledgement

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Thank you

