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Modeling 6-DOF Rigid-Body Motion Of A Thermocapillary Microswimmer

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Thermocapillary Flow

- The surface tension of an air-water interface decreases with increasing temperature
- A gradient in surface tension leads to fluid flow at a fluid-gas or fluidfluid interface
- At small scales, this phenomenon is very efficient, $F \propto L$



Thermocapillary Flow: Implementation

- Most work with thermocapillary flow is done on top of a water surface
- Recently researchers have shown thermocapillary flow with submerged air bubbles
- Flows on the order of cm s⁻¹ have been observed for temperature gradients on the order of °C cm⁻¹



Namura et al (2015) Appl Phys Lett



Proposed Thermocapillary Microswimmer

- By trapping air on the surface of a submerged microswimmer, we may exploit interfacial phenomena
- Imposing a temperature gradient across the swimmer may generate a surface tension gradient
 - Remote heating by AC-magnetic field
- The net force from the surface tension gradient may drive flow around the swimmer, generating propulsion





Geometry: Channel and Swimmer



Main Modules



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Variables and Force-Integrations



Marangoni Swimmer: Overview of the Numerical Setup

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Channel Wall	$\int_{\Sigma A} \begin{bmatrix} (-p\mathbf{I}+\boldsymbol{\tau})\mathbf{n} \\ \mathbf{r} \times (-p\mathbf{I}+\boldsymbol{\tau})\mathbf{n} \end{bmatrix} d\mathbf{A} = 0$
$\mathbf{u} = \mathbf{U} = (\mathbf{V} + \mathbf{\Omega} \times \mathbf{r}) _{\Sigma A}$	=Q _b Cubic Air-Pockets
Constant Con	Microswimmer
$\mathbf{t} \cdot \left[-p\mathbf{I} + \mu \left(\nabla \mathbf{U} + \left(\nabla \mathbf{U} \right)^T \right) - 2/3\mu \left(\nabla \mathbf{U} \right)^T \right] \right]$	$\nabla \cdot \mathbf{U} \mathbf{I} \Big] \cdot \mathbf{n} = \mathbf{t} \cdot \gamma \nabla T$
$\mathbf{x} = (\mathbf{V} + \mathbf{\Omega} \times \mathbf{r}) \Big _{\Sigma \mathcal{A}} \cdot f(x, y, z)$	$\mathbf{u} = \mathbf{U} = 0$ $-\mathbf{n} \cdot \mathbf{q} = 0$

Handling Mesh Deformation **Mesh Deformation** (time-dependent ALE) Channel (Water @ room temp.) **Rubber Mesh Zone** Swimmer Rubber Mesh Envelopes Rubber Mesh Ref: Tabak, A.F., Simulation based experiments of travelling-plane-wave-actuator micropumps and microswimmers, MSc Thesis submitted to Faculty of Engineering and Natural Sciences, Sabanci University, Istanbul, 2007. 10/14/2016

Microswimmer: Simulations

- Mimicked geometry that can be produced by two photon polymerization
 - 100 μm long, 25 μm wide, 10 μm cavities
- Use 30 μW of heating
 - Similar to measured hysteresis loss of 100nm-thick Ni film
- Swimmer propels at 1 body length s⁻¹







Temperature Profile (at the trailing edge)



3 layers with moving mesh 0 [s] <= t <= 1 [s]



Simulation Results: Rectangle Swimmer



Simulation Results: Cylinder Swimmer



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Conclusions and outlook

- Achieved the simulation of rigid-body motion with respect to given heat input,
- Local Marangoni-effect-based flow fields add up to a global flow field,
- Net-thrust is obtained by Marangoni-effect,
- N-S is more suitable to govern the flow field.









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