



Computational method

Figure 5. (a) phase difference between the damping torque and angular velocity, (b) sine and cosine components of damping torque

Figure 6. (a) Damping coefficient versus angular velocity, (b) damping torque versus angular velocity

- The Fluid-Structure Interaction interface was used. •
- 2-D model was developed. Angular displacement ••• $\theta(t) = \theta_0 \sin(\omega t)$ is applied on opposite sides to produce the moment (Figure 3).
- Fluid is in continuum regime and classified as a laminar ••• and incompressible fluid.
- Time domain analysis was performed. •



L (µm)	t (nm)	f (MHz)	T(max) (N.m)	D (N.m.s)	QF
1	200	2.86	8.03E-16	4.47E-20	170
2.5	200	2.01	5.31E-16	4.21E-20	127
5	200	1.47	3.48E-16	3.75E-20	105
1	500	6.33	2.36E-15	5.92E-20	712
2.5	500	4.50	1.47E-15	5.19E-20	578
5	500	3.34	9.57E-16	4.56E-20	488

 Table 1. Summarized simulation results (L=anchors' length, t=thickness, f=resonance)

frequency, T(max)=damping torque, D=damping ratio, Q=quality factor

L (µm)	t (nm)	Sensitivity (Hz/fg)
2.5 (asymmetric)	200	5.58
2.5	200	8.17
2.5	500	10.88

 Table 2. Summarized sensitivity value for
 paddle



Figure 7. Response curve for loaded and unloaded micro paddle

 $-\nabla \cdot \sigma = F v$

Figure 2. Steps to calculate the Quality factor

Figure 3. Applying angular displacement

• Refrence

[1] Boonliang, B., et al., "A focused-ion-beam-fabricated micro-paddle resonator for mass detection." Journal of Micromechanics and <u>Microengineering</u> **18**(1), (2008)

Conclusion

The effect of geometrical parameters on the behavior of the MEMS torsional resonator was investigated. It was shown that by changing these parameters the quality factor could be enhanced which consequently could have significant results on the sensitivity of the sensor. The fabrication of the resonator by Focused ion beam would be the next step to verify these results.

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